

NNNLO zero-jettiness soft function

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1. [Introduction and motivation](#page-2-0)

2. [Ingredients of the final result](#page-6-0)

3. [One-loop corrections with two soft emissions](#page-12-0)

4. [Triple real soft emissions](#page-19-0)

5. [Final result and applications](#page-39-0)

[Introduction and motivation](#page-2-0)

Motivation

- **Differential calculation require a good handle of IR divergences, many schemes exist at NNLO**
- **Slicing scheme seems to be more feasible at N3LO due to non existence of subtraction schemes**

$$
\sigma(O) = \int_0 d\tau \frac{d\sigma(O)}{d\tau} = \int_0^{\tau_0} d\tau \frac{d\sigma(O)}{d\tau} + \int_{\tau_0} d\tau \frac{d\sigma(O)}{d\tau}
$$

$$
- {\rm\ q_T}\ {\rm slicing\ scheme}\\
$$

[−] q^T slicing scheme [Catani,Grazzini'07] [−] N-jettiness slicing scheme [Boughezal et al.'15][Gaunt et al.'15]

SCET factorization theorem motivates us to consider jettiness as a convenient slicing variable for processes with jets in the final state

$$
\lim_{\tau \to 0} d\sigma(O) = B_{\tau} \otimes B_{\tau} \otimes S_{\tau} \otimes H_{\tau} \otimes d\sigma_{LO}
$$

Slicing scheme ingredients

- A phase space is split according to a slicing variable
- **Possible to use any lower order calculation with additional jet in the** $\tau > \tau_{\text{cut}}$ **region**

To apply at the NNNLO level:

[−] Hard function H*^τ*

- [−] Existing NNLO+j calculations
- [−] Many efficient NNLO subtraction schemes

Approximate cross section in the singular region from the factorisation formula

$$
\frac{d\sigma}{d\tau} = H_{\tau} \otimes \{B_{\tau}\} \otimes \{J_{\tau}\} \otimes S_{\tau} \otimes \frac{d\sigma_{0}}{d\tau} + \mathcal{O}(\tau) \qquad \text{=} \text{Beam function } B_{\tau}, \text{ jet function } J_{\tau}
$$
\n
$$
\text{Bermation of the function } B_{\tau} \text{ is the function } S_{\tau} \text{ and the function } B_{\tau} \text{ is the function of the function } S_{\tau} \text{ is the function of the function } S_{\tau} \text{ and the function } S_{\tau} \text{ is the function of the function } S_{
$$

Zero-jettiness measurement function

For two hard partons with momenta p_a and p_b jettiness is defined as follows

$$
\mathscr{T}_0 = \sum_{i=1}^m \min\left\{\frac{2p_a\cdot k_i}{Q}, \frac{2p_b\cdot k_i}{Q}\right\}, \quad k_i-\text{are soft partons}
$$

It is possible to rescale $\rm p_a=\frac{\sqrt{s_{ab}}}{2}n, p_b=\frac{\sqrt{s_{ab}}}{2}\bar{n}$ and go to the frame where $\rm n$ and $\bar{\rm n}$ are back-to-back

Eikonal factors E(k, l) have uniform scaling: rescale integration momenta $q_i = q'_i \frac{Q\tau}{\sqrt{s_{ab}}}$, $q_i \in \{k, l\}$

$$
S(\tau)\sim\int\underset{ext}{\underbrace{\left[d^{d}k\right]^{m}}}\underbrace{\left[d^{d}l\right]^{n}}_{loop}\delta(\tau-\mathcal{P}_{0})E(k,l)\rightarrow\frac{1}{\tau}\left(\frac{s_{ab}}{Q^{2}\tau^{2}}\right)^{e(m+n)}\int\left[d^{d}k'\right]^{m}\left[d^{d}l'\right]^{n}\delta\left(1-\sum_{i=1}^{m}\min\{\alpha_{i},\beta_{i}\}\right)E(k',l')
$$

Sudakov decomposition

$$
k_i=\frac{\alpha_i}{2}n+\frac{\beta_i}{2}\bar{n}+k_{i,\perp},\quad k_i\cdot n=\beta_i,\quad k_i\cdot \bar{n}=\alpha_i,\quad n\cdot \bar{n}=2,\quad n^2=\bar{n}^2=0
$$

[Ingredients of the final result](#page-6-0)

What is actually calculated?

 H, Z, W^{\pm}, \ldots

- **The limit** $\tau \rightarrow 0$ **corresponds to the soft limit of the squared amplitude eikonal Feynman rules**
- Need to include all possible real and virtual corrections to the amplitude squared

 $\frac{\gamma}{2}$, $\frac{Z_{1}}{Z_{2}}$

- **Possible to combine different measurement function terms into unique configurations**
- **Perform integration over highly non-trivial region all kinds of divergencies are possible**

From measurement function to configurations

- **Minimum function is a problem for analytic calculation**
- **Definition which is more friendly for phase-space integration generates many configurations**

$$
\delta\left(1-\sum_{i=1}^m\min\{\alpha_i,\beta_i\}\right)=\delta(1-\beta_1-\beta_2-\dots)\theta(\alpha_1-\beta_1)\theta(\alpha_2-\beta_2)\dots+\delta(1-\beta_1-\alpha_2-\dots)\theta(\alpha_1-\beta_1)\theta(\beta_2-\alpha_2)\dots
$$

- Configurations can be mapped to the minimal set due to symmetries of Eikonal factor and $\delta(1 {\alpha, \beta})$
- RVV single configuration with $\delta(1 k \cdot n)$, trivial phase-space integration
- [−] Two-loop soft current is known [Duhr, Gehrmann'13] RRV two configurations nn and nn [−] Emission of gluons and quark pair [Chen et al.'22] [Baranowski et al.'24] RRR two configurations nnn and nnn [−] Same hemisphere gluon emission [Baranowski et al.'22] [−] Different hemispheres configuration nnn¯ and quark pair emission in nnn configuration - this work [Intro](#page-2-0) [Details](#page-6-0) [RRV](#page-12-0) [RRR](#page-19-0) [Results](#page-39-0)

[Intro](#page-2-0) [Details](#page-6-0) [RRV](#page-12-0) [RRR](#page-19-0) [Results](#page-39-0)

Calculation strategy

- 1. There are many highly non-trivial integrals, which we can calculate with direct integration
	- [−] All integrations are divergent at the boundaries only
	- [−] All integrals are linear reducible, GPLs only at all steps
	- [−] Once there is a way to subtract divergencies integrals calculated with HyperInt [Panzer'15]

- 2. Utilization of the modern multi-loop calculation techniques to reduce the problem to (1)
	- [−] Reduction of integrals to the minimal set of master integrals
	- [−] Differential equations for integrals at the expense of introducing new parameters
	- [−] Symmetry relations between integrals
	- [−] Input expression organization in "diagram"-like structures

Relative complexity of ingredients

RVV corrections

Two-loop corrections $r^{(2)}_{\rm S}$ to single gluon emission soft current are known exactly in ϵ [Duhr, Gehrmann'13] k n \bar{n} $=$ r_S(k) $\sqrt{2}$ Ł L L \mathbf{I} k + --- $\begin{pmatrix} k \\ k \end{pmatrix}$ n \bar{n} n \bar{n} λ $\overline{}$ $\overline{1}$, $r_S(k) = 1 + \sum_{k=1}^{\infty}$ $l=1$ $A_s^1\left[\frac{-(n \cdot \bar{n})}{2(k \cdot n)(k)}\right]$ $2(k \cdot n)(k \cdot \bar{n})$ \int_{0}^{∞} r_S⁽¹⁾

Two contributions from different hemisphere emissions need to be integrated, ${\rm S_g^{(3)}} = {\rm s}_{2,0} + {\rm s}_{1,1} + {\rm s}_{0,2}$

$$
s_{l,m} = \int \frac{d^dk}{(2\pi)^{d-1}} \delta^+\left(k^2\right) \left[\delta(1-k\cdot n)\theta(k\cdot \bar{n}-k\cdot n) + \delta(1-k\cdot \bar{n})\theta(k\cdot n-k\cdot \bar{n})\right] w_{L,M}(k)
$$

[One-loop corrections with two soft emissions](#page-12-0)

One-loop corrections with double emission

- **RRV** squared amplitudes generated from scratch
- Results for one-loop soft current are known [Zhu'20][Czakon et al.'22]
- RRV result for gg final state were computed earlier [Chen, Feng, Jia, Liue'22]
- Recalculation in the unified way including $q\bar{q}$ final state [Baranowski et al. '24]
-

Multi-loop calculations inspired approach

- Reduction to the minimal set of master integrals with loop and phase-space integration
- Differential equations from IBP reduction parameter to differentiate is needed

Modified reverse unitarity to deal with *θ*-integrals

In dimensional regularisation system of IBP equation can be constructed by differentiation under integral sign

$$
\int d^d \mathbf{1} \frac{\partial}{\partial \mathbf{1}_{\mu}} \left[\mathbf{v}_{\mu} \cdot \mathbf{f}(\{\mathbf{1}\}) \right], \qquad \frac{\partial}{\partial \mathbf{k} \cdot \bar{\mathbf{n}}} \theta(\mathbf{k} \cdot \bar{\mathbf{n}} - \mathbf{k} \cdot \mathbf{n}) = \delta(\mathbf{k} \cdot \bar{\mathbf{n}} - \mathbf{k} \cdot \mathbf{n})
$$

IBP for integrals with *θ*-functions generate new auxiliary topologies, partial fractioning required

$$
\frac{\theta(k \cdot \bar{n} - k \cdot n)}{(k \cdot \bar{n})^a (k \cdot n)^b} \rightarrow \frac{\delta(k \cdot \bar{n} - k \cdot n)}{(k \cdot \bar{n})^a (k \cdot n)^b}
$$

\n
$$
= \text{RRR} \underbrace{\theta \theta \theta}_{\text{Level 3}} \rightarrow \underbrace{\delta \theta \theta + \theta \delta \theta + \theta \theta \delta}_{\text{Level 2}} \rightarrow \underbrace{\delta \delta \theta + \delta \theta \delta + \theta \delta \delta}_{\text{Level 1}} \rightarrow \underbrace{\delta \delta \delta}_{\text{Level 0}}
$$
\n

\n\n
$$
= \text{RRV} \underbrace{\theta \theta}_{\text{Level 2}} \rightarrow \underbrace{\delta \theta + \theta \delta}_{\text{Level 1}} \rightarrow \underbrace{\delta \delta}_{\text{Level 0}}
$$
\n

\n\n
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= \text{RRV} \underbrace{\theta \theta}_{\text{Level 2}} \rightarrow \underbrace{\delta \theta + \theta \delta}_{\text{Level 1}} \rightarrow \underbrace{\delta \delta}_{\text{Level 0}}
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= \text{RRV} \underbrace{\theta \theta}_{\text{Level 2}} \rightarrow \underbrace{\delta \theta + \theta \delta}_{\text{Level 1}} \rightarrow \underbrace{\delta \delta}_{\text{Level 0}}
$$
\n

 \cdot

RRV master integrals calculation

■ Number of MIs after IBP reduction of both configurations in RRV case

Direct integration possible, except pentagon and box with $a_3 = 0$

■ DE in auxiliary parameters for most complicated integrals

Original integrals from DE solution

Additional parameter z is not needed - utilize variables from integral representation

• To recover integrals of interest I instead of taking limit
$$
I = \lim_{z \to z_0} J(z)
$$
 we integrate $I = \int dz J(z)$

RRV master integrals from differential equations

For $\delta\delta$ integrals we introduce auxiliary parameter x and solve DE system $\partial_x J(x) = M(\varepsilon, x)J(x)$

$$
I_{\delta\delta} = \int d(k_1 \cdot k_2) f(k_1 \cdot k_2) = \int_0^1 dx \int d(k_1 \cdot k_2) \delta(k_1 \cdot k_2 - \frac{x}{2}) f(k_1 \cdot k_2) = \int_0^1 J(x) dx
$$

For $\delta\theta$ and $\theta\delta$ we use integral representation for θ -function and solve DE system $\partial_x J(z) = M(\varepsilon, z)J(z)$

$$
\theta(b-a) = \int_0^1 b\delta(zb-a)dz, \quad I_{\delta\theta} = \int_0^1 J(z)dz
$$

For $\theta\theta$ integrals PDE system in two variables $\rm z_{1}, \rm z_{2},$ no IBP reduction with θ -functions needed

$$
I_{\theta\theta} = \int_0^1 dz_1 \int_0^1 dz_2 J(z_1, z_2)
$$

Differential equations in canonical form

- **For all auxiliary integrals it is possible to find alternative basis of integrals, such** ε **dependence of the DE system matrix** factorizes completely: $M(\varepsilon) \to \varepsilon A$ [Henn'13]
- Straightforward solution for integrals in canonical basis in terms of GPLs
- **Simpler boundary conditions fixing due to known general form of expansion near singular points**

$$
g(z) = z^{a_1+b_1\varepsilon} (c_1 + \mathcal{O}(z)) + z^{a_2+b_2\varepsilon} (c_2 + \mathcal{O}(z)) + \dots
$$

Construction of subtraction terms to remove endpoint singularities in the final integration

$$
\int_0^1 J(z)dz = \int_0^1 \underbrace{[J(z) - z^{a_1 + b_1 \varepsilon}j_0(z) - (1 - z)^{a_k + b_k \varepsilon}j_1(z)]}_{\varepsilon - \text{expanded}} dz + \int_0^1 \underbrace{(z^{a_1 + b_1 \varepsilon}j_0(z) - (1 - z)^{a_k + b_k \varepsilon}j_1(z))}_{\varepsilon - \text{exact}} dz
$$
\nNext

\nNext

\nNext

\nNext

\nResults

\nResults

Summary: real-real-virtual contributions

- **IBP** reduction of integrals with θ-functions and loop integration can be efficiently implemented
- **Differential equations for auxiliary integrals can be constructed and solved analytically**
- Auxiliary integrals are simplified in the limit, and all required boundary constants can be calculated

[Triple real soft emissions](#page-19-0)

Triple real emissions

Recalculated input for eikonal factors with partial fractioning and topology mapping

- gg = ggg + gc \bar{c} , coincides with the known expression in physical gauge \lceil Catani,Colferai,Torrini'19]
-

Same hemisphere

 $δ(τ - β₁ - β₂ - β₃)$

Same hemisphere result for ggg final state is known [Baranowski et al. '22]

■ gqq̄ in agreement with **[Del Duca,Duhr,Haindl,Liu'23]**

Different hemispheres

δ(*τ* − *β*₁ − *β*₂ − *α*₃)

Divergences unregulated dimensionally

- Same hemisphere emission of $\mathrm{k}_1, \mathrm{k}_2$ partons
- Integration in the region β_1 |{z} ∼*λ* $<< \alpha_1, \beta_2$ \sim_1 $<<$ α_2 |{z} ∼1*/λ*
- Both are close to the \vec{n} direction cos $\theta_1 \sim \cos \theta_2 \sim 1 + \mathcal{O}(\lambda)$
- And large energies difference $ω_1$ ~ 1 << $ω_2$ ~ 1/λ

Possible cases for integrals in the potentially unregulated region

Additional regulator in action

- Example region k_1, k_2 : $\beta_1 \sim \lambda$ and $\alpha_2 \sim 1/\lambda$ change of variables $\beta_1 = \xi_1 \alpha_1$ and $\alpha_2 = \beta_2/\xi_2$
- Our choice for regulator to modify integration measure for each $dk_i\theta(a_i-b_i)\rightarrow dk_i\theta(a_i-b_i)b_i^{\nu}$

$$
\int \frac{d\alpha_1 d\beta_1 d\alpha_2 d\beta_2 (\beta_1 \beta_2)^{\nu}}{(\alpha_1 \beta_1 \alpha_2 \beta_2)^{\varepsilon}} \to \begin{cases} \int d\alpha_1 d\beta_2 dxd\xi_2 \frac{(\alpha_1 \beta_2)^{1-2\varepsilon+\nu}}{\xi_2^{1-\gamma}\kappa^{\varepsilon-\nu}} & , \xi_1 < \xi_2, \xi_1 = x\xi_2 \\ \int d\alpha_1 d\beta_2 dxd\xi_1 \frac{(\alpha_1 \beta_2)^{1-2\varepsilon+\nu}}{\xi_1^{1-\gamma}\kappa^{2-\varepsilon}} & , \xi_2 < \xi_1, \xi_2 = x\xi_1 \end{cases}
$$

- Additional complications due to a new regulator
	- [−] More complicated reduction due to an additional parameter in the problem
	- $-$ Master integrals calculation is more difficult due to the need to consider the double limit *ε*, *ν* → 0

Reduction of *ν*-regulated integrals

Approaches to *ν*-dependent IBP reduction problem (IBP with *ν* is available)

- 1. Direct *ν*-dependent reduction with additional variable
	- ✘ Time consuming and not flexible especially if basis change needed
	- ✔ Minimal set of master integrals and full *ν*-dependent solution
- 2. Filtering remove all equations with potentially divergent integrals from the IBP system
	- ✔ Very fast compared to the full *ν*-dependent reduction
	- ✘ Potentially unreduced integrals, needs divergencies analysis for all integrals in the IBP system
- 3. Expansion rewrite IBP system as a new system for 1*/ν* expansion coefficients of integrals
	- \blacktriangleright Fast reduction with control of divergencies
	- ✘ Additional divergent parts of integrals from the intermediate steps of IBP reduction can appear

Importance of a good master integrals basis

- From the analysis of possible divergencies we consider ansatz $\mathrm{~J}_{\mathrm{a}}=\frac{\infty}{\sum}$ $k= k_0$ $J_a^{(k)} \nu^k$ with $k_0 = -1$
- Solution of the IBP reduction problem for regular-*ν* integrals I_a has the form

$$
I^{(0)}_a\,{=}\,R_{ab}\,J^{(0)}_b\,{+}\,D_{ab}\,\tilde J^{(-1)}_b
$$

- We require a "good" basis to fulfill the following conditions:
	- [−] Coefficients in front of master integrals do not contain 1*/ν* poles
	- $^-$ Each master integral is a member of only one set $\rm J_b$ or $\rm \tilde{J}_b$
	- [−] Candidates for the set J_b can be found from the *ν* = 0 reduction
- Regular integrals $J_{\rm b}^{(0)}$ are calculated in a standard way, calculation of needed divergent parts $\tilde J_{\rm b}^{(-1)}$ is simplified, since only specific regions contribute

DE for RRR integrals with auxiliary mass

- Integrals for both \min and \min configurations with denominator $1/k_{123}^2$ are difficult to calculate
- Since integrals are single scale, auxiliary parameter is needed to construct the system of DE I \rightarrow $\rm J(m^2)$
- We modify the most complicated propagator $\frac{1}{(k_1+k_2+k_3)^2} \rightarrow \frac{1}{(k_1+k_2+k_3)^2+m^2}$
- Calculation of boundary conditions is possible in the limit $m^2 \rightarrow \infty$, but still very difficult
- Massless integrals I are obtained from the solution for ${\rm J(m^2)}$ in the limit ${\rm m^2}\!\rightarrow\!0,$ which is not trivial

Difficulties of the chosen strategy

- Both points $m^2 \to 0$ and $m^2 \to \infty$ are singular points of the DE system
- Solution of the DE for integrals with massive denominator is only possible numerically

Details of the DE solution

- A much larger DE system, \sim 650 equations are needed for nnn configuration compared to \sim 150 for nnn
- Need to calculate all contributing regions into boundary conditions in the $m^2 \to \infty$ limit

- **■** For each large parameter $\alpha_i \sim m^2$ we remove $\theta \implies$ additional IBP reduction of boundary conditions integrals possible
- Numerical solution of the DE system as a sequence of series expansions [Liu et al. '18][Chen et al. '22]

From boundaries at $m^2 \to \infty$ to $m^2 \to 0$ solution

- Sum of all regions at $m^2 \to \infty$ to get high precision numerical solution at the first regular point R_{∞}
- High precision numerical solution of the DE between seqence of regular point $\rm R_{\infty} \to R_1\ldots R_n \to R_0$
- Final result Taylor branch of the generalized $m^2 \rightarrow 0$ expansion gives the required result

Nice features of the DE and its solution

- Numerical DE solution at finite $m²$
	- $-$ Independent numerical checks at finite m^2
- **Local Fuchsian form of the DE near singular points** $m^2 \to 0$ **and** $m^2 \to \infty$
	- [−] Matrix solution and generalized power series expansions
	- [−] Minimal set of independent boundary constants to calculate
- Self-consistency checks of the DE solution and boundaries
	- [−] Unphysical branches disappear after boundaries substitution
	- − On the real axis m^2 ∈ $(0, \infty)$ all integrals have zero imaginary parts
- Relations between specific branch expansion coefficients and IBP reduction of boundary constants
- Massless integrals we are interested in are extracted from the specific branch of $m^2 \to 0$ DE solution

Boundaries at $m^2 \rightarrow \infty$ and series expansions

Local Fuchsian form of the transformed DE with $\vec{f} = T \vec{g}$ and $y = y(m^2)$

$$
\frac{\partial \vec{g}}{\partial y} = \left[\frac{A_0}{y} + \sum_i \frac{A_i}{P_i(y)} \right] \vec{g}, \quad P_i(0) \neq 0
$$

Leading order matrix solution \vec{g} (y) $=$ U(y) \vec{B} directly read from the Fuchsian DE: U(y \rightarrow 0) \sim y A_0

Specific branch y^{λ} expansions, $\lambda = b\varepsilon$

 $J_1^{(\lambda)} = y^{a_1 + \lambda} \left(c_{1,0}^{\lambda} + c_{1,1}^{\lambda} y^1 + c_{1,2}^{\lambda} y^2 + \dots \right)$

. . .

$$
J_n^{(\lambda)}=y^{a_n+\lambda}\left(c_{n,0}^\lambda+c_{n,1}^\lambda y^1+c_{n,2}^\lambda y^2+\dots\right)
$$

- We are interested in $y = m^2$ and $y = 1/m^2$
- Minimal vector $\vec{\textbf{B}}$ is a subset of $\bigcup_{\lambda}\{c_{1,0}^{\lambda},\ldots,c_{n,0}^{\lambda}\}$
- All $\mathrm{c}_{\mathrm{i,j}}^{\lambda}$ with $\mathrm{j} > 0$ through subset of $\mathrm{c}_{\mathrm{i,0}}^{\lambda}$
- Reducible integrals expansion coefficients reduction

IBP reduction of boundary constants at $m^2 \to \infty$

Local Fuchsian form ⇒ Matrix series solution ⇒ IBP for constants

- 1. Available IBP reduction tables for massive integrals $X_i = \sum R_{i,k}(m^2) J_k$ k
- 2. Deep enough $1/\rm{m}^2$ expansions for master integrals $\rm J_k$ due to possible poles/zeroes in $\rm R_{i,k}(m^2)$
- 3. Substitution of expanded MIs and unknown integrals $X_i = \sum X_i^{(\lambda)}$ to IBP tables provides relations between leading expansion coefficients $\mathrm{x}_{\mathrm{i,0}}^{\lambda}$ and $\mathrm{c}_{\mathrm{j,0}}^{\lambda}$ valid for each branch $(\mathrm{m}^2)^{\lambda}$ independently

$$
X^{(\lambda)}_i\,{=}\,(m^2)^{a_1{+}\lambda}\Bigg(x_{i,0}^\lambda+\frac{x_{i,1}^\lambda}{m^2}+\frac{x_{i,2}^\lambda}{m^4}+\dots\Bigg)
$$

- **In each region additional boundary constants calculated and checked against reduction prediction**
- Due to huge difference in calculation complexity possible to select simpler/less divergent integrals

Boundary integrals simplification

Main difficulty comes from the dependence of $\rm k_{123}^2+m^2$ on three angles, but in specific regions simplifications occur

$$
k_{123}^2+m^2=\sum_{i\neq j}\alpha_i\beta_j-\sqrt{\alpha_i\beta_i\alpha_j\beta_j}\cos\left(k_{i,\perp},k_{j,\perp}\right)+m^2
$$

Region $\left(\mathrm{m}^{2}\right) ^{-\varepsilon}$, single large parameter e.g. $\alpha_{1}\thicksim\mathrm{m}^{2}$

 $k_{123}^2 + m^2 \rightarrow \alpha_1 (\beta_2 + \beta_3) + m^2$

Region $\left(m^2\right)^{-2\varepsilon}$, pair of large parameters e.g. $a_1\thicksim a_2\thicksim$ m^2 , angle dependence remains since $\mathrm{k}_1\cdot\mathrm{k}_2\thicksim$ m^2

$$
k_{123}^2 + m^2 \rightarrow k_{12} + (\alpha_1 + \alpha_2)\beta_3 + m^2
$$

Boundary constants in the region $\text{(m}^2)^{-\varepsilon}$

- Dependence on angles disappears in $k_{123}^2 + m^2 \to a_i (\beta_j + \beta_k) + m^2$ in the $m^2 \to \infty$ limit
- Only non-trivial scalar product for e.g. $\alpha_1 \sim m^2$ is $(k_2 \cdot k_3)$ and $\theta(\alpha_1 \beta_1) \to 1$
- Integration over the relative angle between soft partons in terms of $_2{\rm F}_1$, function of argument dependent on $r_i = \frac{\beta_i}{\alpha_i} \theta(\alpha_i - \beta_i) + \frac{\alpha_i}{\beta_i} \theta(\beta_i - \alpha_i)$
- For same-hemisphere emissions we split integration region into $r_i > r_i$ and $r_i < r_i$

Boundary constants in the region $\rm (m^2)^{-2g}$

- For two large parameters, say $a_1 \sim a_2 \sim$ $\rm m^2$ integrations become unconstrained $\theta(a_1-\beta_1)\theta(a_2-\beta_2)\to 1$
- Turn boundary integrals into ordinary PS integral ${\rm J}$ using $1\,{=}\int{\rm d}{\rm q}\delta({\rm q}\,{-}\,{\rm k}_1\,{-}\,{\rm k}_2)$ insertion

$$
\begin{aligned} L_{2\varepsilon} = \int \frac{\mathrm{dqdk}_3 \delta(1-\beta_{\rm q}-\beta_3)\mathscr{C}_3}{q^2+\alpha_{\rm q}\beta_3+m^2} \times \frac{1}{\prod_{\rm i}D_{\rm i}\left(\alpha_{\rm q},\beta_{\rm q},q^2,\alpha_3,\beta_3\right)} \times J_{a_1\ldots a_6}\left(\beta_3,\alpha_{\rm q},\beta_{\rm q},q^2\right)} \\ J_{a_1\ldots a_6} = \int \frac{[\mathrm{d}k_1] [\mathrm{d}k_2] \, \delta\left(k_1^2\right) \delta\left(k_2^2\right) \delta^{(\mathrm{d})}\left(q-k_1-k_2\right)}{(k_1\cdot n)^{a_1}\left(k_2\cdot n\right)^{a_2}\left(k_1\cdot \bar{n}\right)^{a_3}\left(k_2\cdot \bar{n}\right)^{a_4}\left(k_1\cdot n+\beta_3\right)^{a_5}\left(k_2\cdot n+\beta_3\right)^{a_6}} \end{aligned}
$$

IBP reduction possible, nontrivial part in the angular integral $\Omega_{\rm n}=\int \frac{\rm d\Omega_{\rm k}}{({\rm k}\cdot {\rm v}_1)^{a_1}({\rm k}\cdot {\rm v}_2)^{a_2}...({\rm k}\cdot {\rm v}_{\rm n})^{a_{\rm n}}}$

- After partial fractioning only $\Omega_{\rm n}$ with ${\rm n=1,2}$ and maximum single ${\rm v}_{\rm i}^2\neq 0$ and all other ${\rm v}_{\rm j}^2=0$
- Trivial integration over large parameter $a_{\rm q}\,{\sim}\,\text{m}^2$, linear propagators simplified e.g. $a_1+\alpha_3\to a_1$

Direct integration of MIs and boundary constants

- We have calculated \sim 130 integrals without $1/{\rm k}_{123}^2$ denominator and \sim 100 boundary conditions by direct integration with HyperInt [Panzer'15]
- **Summary of used techniques**
- 1. Change variables to satisfy all constraints from *δ* and *θ* functions
- 2. Perform as many integrations as possible in terms of $_2\mathrm{F}_1$ and F_1 functions with known transformation properties
- 3. Perform remaining integrations in terms of $_{\text{p}}\text{F}_{\text{q}}$ functions if possible
- 4. For the final integral representation with minimal number of integrations and minimal set of divergencies construct subtraction terms
- 5. Integrand with all divergencies subtracted is expanded in ε and integrated term by term with HyperInt
- 6. Subtraction terms are integrated in the same way

Numerical checks of calculated integrals

- For integrals without $1/k_{123}^2$ denominator use parametrisation similar to one used for analytical calculation
	- − Straightforward hyper-cube parametrisation due to simple angle dependence of $1/\big(\rm{k}_i\cdot k_j\big)$ denominators only
	- $\texttt{-}$ Sector decomposition with remapping $\text{x} \to 1$ divergencies to $\text{x}' \to 0$ with $\texttt{pySecDec}$ or \texttt{FIESTA}
- For integrals with $1/k_{123}^2$ at $\mathrm{m}^2=0$ we avoid the need to use angles and construct Mellin-Barnes representation
	- [−] Repeated application of (A + B) *^λ* → R A*^λ*1B *^λ*² , important to have A,B *>* 0 at each step
	- [−] Angle integration simplified until can be integrated in terms of gamma functions only
	- [−] Analytical continuation with MBresolve and numerical integration with MB
- Integrals with $1/k_{123}^2$ at finite m^2 , which are less divergent due to mass regularization
	- [−] Careful preselection of less divergent integrals using available reduction to prevent SD from complexity explosion
	- [−] For finite integrals or integrals with factorized divergencies direct integration with subtraction
	- − Midpoint splitting for $x_i \rightarrow 1$ divergencies and sector decomposition for overlapping divergencies using FIESTA

Mellin-Barnes representation for angular integral

First we convert complicated denominator $1/k_{123}^2$ into product of scalar products

$$
\frac{1}{(k_1\cdot k_2+k_2\cdot k_3+k_3\cdot k_1)^{\lambda}}=\frac{1}{\Gamma(\lambda)}\int\limits_{c-i\infty}^{c+i\infty}\frac{dz_1dz_2}{(2\pi i)^2}\frac{\Gamma(\lambda+z_1+z_2)\Gamma(-z_1)\Gamma(-z_2)}{(k_1\cdot k_2)^{z_1+z_2+\lambda}(k_2\cdot k_3)^{-z_1}(k_3\cdot k_1)^{-z_2}}
$$

Introduce unit length vectors to make standard angular integral structure transparent

$$
\frac{1}{(k_i \cdot k_j)^{\lambda}} = \frac{1}{\Gamma(\lambda)} \int_{c-i\infty}^{c+i\infty} \frac{dz}{2\pi i} \Gamma(-z) \Gamma(\lambda + z) \frac{2^{-z} \left(\sqrt{\alpha_i \beta_j} - \sqrt{\alpha_j \beta_i}\right)^{2z}}{\left(\alpha_i \beta_i \alpha_j \beta_j\right)^{z/2 + \lambda/2}} \frac{1}{(\rho_i \cdot \rho_j)^{z+\lambda}}, \quad \rho_i = \left(1, \frac{\vec{k}_{i,\perp}}{|\vec{k}_{i,\perp}|}\right)
$$

Final angles integration can be done in closed form well suited for subsequent MB integrations

$$
\int \frac{\mathrm{d}\Omega_1 \mathrm{d}\Omega_2 \mathrm{d}\Omega_3}{(\rho_1 \cdot \rho_2)^{\lambda_1} (\rho_2 \cdot \rho_3)^{\lambda_2} (\rho_3 \cdot \rho_1)^{\lambda_3}} = \frac{\Gamma^3(1-\varepsilon)}{\pi^{3/2} 2^{6\varepsilon+\lambda} \Gamma(1-2\varepsilon)} \frac{\Gamma(1-2\varepsilon-\lambda)}{\prod\limits_{i=1}^3 \prod\limits_{j=1}^{i-1} \Gamma\big(1-2\varepsilon-\lambda_i-\lambda_j\big)}
$$

Finite mass integrals

Use angles between transverse momenta as parameters

$$
(\mathbf{k}_i \cdot \mathbf{k}_j) = 1/2 \left(\sqrt{\alpha_i \beta_j} - \sqrt{\alpha_j \beta_i}\right)^2 + \sqrt{\alpha_i \beta_i \alpha_j \beta_j} \rho_{ij}
$$

$$
\rho_{12} = (1 - \cos \theta_1) \quad \rho_{13} = (1 - \cos \theta_2) \quad \rho_{23} = (1 - \cos \theta_1 \cos \theta_2 - \sin \theta_1 \sin \theta_2 \cos \theta_3)
$$

Integral divergences analysis

- **u** $x_i \in [0, 1] \rightarrow z_i \in [0, \infty)$, div: $\{z\} \rightarrow 0$ or $\{z\} \rightarrow \infty$
- Possible subsets Z_0 and Z_{∞} of $\{z_1, \ldots, z_n\}$
- Do rescalings $z_i \to \lambda z_i$, $z_i \in Z_0$ and $z_i \to 1/\lambda z_i$, $z_i \in Z_{\infty}$
- Divergent if for $\int \frac{dz}{z^a} \prod P(z)^b \to \lambda^w \int \frac{dz}{z^a} \prod P(z)^b$

$$
w + \dim (Z_0) - \dim (Z_\infty) \le 0
$$

■ For all integrals with $Z_{\infty} \neq \emptyset$ split at point $0 < p < \infty$

$$
\int_{0}^{\infty} dz f(z) = p \int_{0}^{\infty} \frac{dz}{(1+z)^2} f\left(\frac{pz}{1+z}\right) + p \int_{0}^{\infty} \frac{dz}{z^2} f\left(\frac{p(1+z)}{z}\right)
$$

Select less divergent integrals determined by all Z_0 sets

Summary: triple-real contributions

- Additional regulator is required for correct IBP reduction
- **Efficient techniques are developed to decrease the complexity of the reduction with additional regulator**
- DE for auxiliary m^2 dependent integrals with $1/\mathrm{k}_{123}^2$ propagator makes calculation possible
- **DE** in addition to numerical solution also provides many important consistency checks and relations
- **Integrals are highly non-trivial for numerical checks**

[Final result and applications](#page-39-0)

Laplace space and UV renormalization

Final unrenormalized result for the NNNLO soft function is a sum over configurations C

$$
S_{\tau,B}^{\rm NNNLO} = \sum_C S_{\tau,B}^{\rm RVV,C} + \sum_C S_{\tau,B}^{\rm RRV,C} + \sum_C S_{\tau,B}^{\rm RRR,C}
$$

For the renormalization we need the NNLO result expanded to higher orders in ε [Baranowski'20]

$$
S_{\tau,B} = \delta(\tau) + \frac{a_{s,B}}{\tau} \bigg(\frac{s_{ab}}{Q^2 \tau^2} \bigg)^{\!\!\!s} \, S_1 + \frac{a_{s,B}^2}{\tau} \bigg(\frac{s_{ab}}{Q^2 \tau^2} \bigg)^{\!\!\!2\epsilon} \, S_2 + \frac{a_{s,B}^3}{\tau} \bigg(\frac{s_{ab}}{Q^2 \tau^2} \bigg)^{\!\!\!3\epsilon} \, S_3 + \mathscr{O} \! \left(a_{s,B}^4 \right)
$$

Do strong coupling renormalization $a_{s,B}=\mu^{2e}Z_{a_s}a_s(\mu)$ and do Laplace transform with parameter $\bar u=ue^{\gamma_E}$

[Intro](#page-2-0) [Details](#page-6-0) [RRV](#page-12-0) [RRR](#page-19-0) [Results](#page-39-0)

$$
\tilde{S}_B\left(a_s(\mu),L_S\right) = \int\limits_0^\infty d\tau e^{-\tau u} \, S_{\tau,B}\left(a_{s,B}\to \mu^{2\epsilon} Z_{a_s} a_s(\mu)\right), \quad L_S = \ln\left(\mu \bar{u} \frac{\sqrt{s_{ab}}}{Q}\right)
$$

Convenient to consider $\rm \tilde{S}_B$ because the renormalization in Laplace space is multiplicative

Renormalization and checks from RG equation

Multiplicative renormalization in the Laplace space with $\rm L_S$ dependent renormalization constant $\rm Z_s(a_s,L_S)$

$$
\tilde{S}(a_s, L_S) = Z_s(a_s, L_S)\tilde{S}_B(a_s, L_S) = \mathcal{O}(\varepsilon^0)
$$

$$
- L_S = \ln\left(\mu \bar{u} \frac{\sqrt{s_{ab}}}{Q}\right)
$$

 $\rm Z_s$ determined by the pole part of $\rm \tilde{S}_B$ satisfies RG equation

35/41 18. 11. 2024 Andrey Pikelner: N3LO 0-jettiness soft function Andrey Pikelner: N3LO 0-jettiness soft function

∂

 $\frac{\partial}{\partial L_{\rm S}} + \beta(a_{\rm s}) \frac{\partial}{\partial a_{\rm s}}$

 $\partial \operatorname{a}_{\mathrm{s}}$

 $^ \,\mu$ dependence in $\mathrm{a_s}(\mu)$ and $\mathrm{L_S}$

- $\Gamma_{\rm s}$ is finite
- [−] Known cusp an.dim γ_{cusp}
- [−] Known non-cusp an.dim *γ*^s
- Possible to make prediction for the NNNLO pole part of $\rm \tilde{S}_B$ and therefore for $\rm S_{\tau,B}$ from the NNLO result
- Final form of the renormalized NNNLO soft function can be split into constant and L_S dependent parts

 $\ln Z_{\rm s}({\rm a_s,L_S}) = \Gamma_{\rm s}({\rm a_s,L_S}) = -4\gamma_{\rm cusp}({\rm a_s)L_S} - 2\gamma_{\rm s}({\rm a_s})$

ln S˜(a^s ,LS) = X∞ i=1 X2i j=0 Cija i s L j ^S ⁼ ln S˜ + X∞ i=1 X2i j=1 Cija i s L j S , S˜ = S˜(a^s , 0) [Intro](#page-2-0) [Details](#page-6-0) [RRV](#page-12-0) [RRR](#page-19-0) [Results](#page-39-0)

Result for NNNLO zero-jettiness soft function

Eikonal line representation dependence completely factorizes at NNNLO due to Casimir scaling

$$
\frac{\ln(\tilde{S})}{C_R} = -a_s \pi^2 + a_s^2 \left[n_f T_F \left(\frac{80}{81} + \frac{154\pi^2}{27} - \frac{104\zeta_3}{9} \right) - C_A \left(\frac{2140}{80} + \frac{871\pi^2}{54} - \frac{286\zeta_3}{9} - \frac{14\pi^4}{15} \right) \right] \n+ a_s^3 \left[n_f^2 T_F^2 \left(\frac{265408}{6561} - \frac{400\pi^2}{243} - \frac{51904\zeta_3}{243} + \frac{328\pi^4}{1215} \right) + n_f T_F (C_F X_{FF} + C_A X_{FA}) + C_A^2 X_{AA} \right] + \mathcal{O}\left(a_s^4\right)
$$

With $a_{\rm s}=\frac{a_{\rm s}}{4\pi}$ and new coefficients calculated numerically with high precision

 $X_{FF} = 68.94258498$ $X_{FA} = 839.72385238$ $X_{AA} = -753.77578727$

Soft function constants in $n_f = 5$ QCD required for resummed predictions (q : C_R → C_F) and (g : C_R → C_A)

$$
c_3^{S,q} = -1369.575849 \qquad c_3^{S,g} = -3541.982541
$$

Singular region cross section from MC simulation

- **Fit in the region, where NNLO MC predictions and approximate factorization prediction overlap**
- From the condition ${\rm R}(\tau)$ + $\bar{{\rm R}}(\tau)$ $=$ 1 and all ${\rm C}_{\rm i}, {\rm G}_{\rm ij}$ except ${\rm C}_{\rm 3}$ known

$$
R(\tau)\!=\!\left(1+\sum_{k=1}^{\infty}C_k\!\left(\frac{\alpha_s}{2\pi}\right)^{\!k}\right)\!\exp\left[\sum_{i=1}^{\infty}\!\sum_{j=1}^{i\!+\!1}\!G_{ij}\left(\frac{\alpha_s}{2\pi}\right)^{\!i} \ln^j\frac{1}{\tau}\right]
$$

Missing C_3 in the parametrisation of dijet region for NNLO Thrust $[\mathrm{Monni\,Gehrmann,Luisoni\,{}'11}]$

From soft function to singular cross section

- Coefficient C3 is determined by constant parts of Hard(H), $|et($]) and Soft(S) functions
	- $-$ N3LO hard function is known $\rm c_3^H$
	- $-$ N3LO jet function known $\rm c_3^J$
- From $\rm C_3$ value can determine $\rm c_3^S$, since all other ingredients are known $\rm [Brüser, Liu, Stahlhofen'18]$

$$
c_3^S = \begin{cases} -19988 \pm 1440 \pm 4000 & \text{fit result} \\ -1369.57 & \text{this work, exact} \end{cases}
$$

Inverse of the relation with known $\mathrm{c}_3^{\mathrm{S}}$ allows C_3

³ ⁼ [−]128.⁶⁵¹ [Brüser,Liu,Stahlhofen'18]

[Abbate,Fickinger,Hoang et al.'10]

[Monni,Gehrmann,Luisoni'11]

Applications

- Thrust resummation for $\alpha_{\rm s}$ determination, missing ingredient $c_3^{\rm S}$ is now available
	- c_2^S
	- [−] c H 3 known, fitted c J 3 , c S 3
	- $\sim {\rm c}_{3}^{\rm H}, {\rm c}_{3}^{\rm J}$ known, attempt to extract ${\rm c}_{3}^{\rm S}$
- Higgs decay to quarks/gluons *α*^s series convergence restored [Ju,Xu,Yang,Zhou'23]

$$
\tilde{s}_g = 1 - 2.36\alpha_s + 1.617\alpha_s^2 - \underbrace{(22.89 \pm 5.67)}_{\text{fit}}\alpha_s^3
$$

■ Differential N3LO jet production in DIS and VBF

[Intro](#page-2-0) [Details](#page-6-0) [RRV](#page-12-0) [RRR](#page-19-0) [Results](#page-39-0)

[Becher,Schwartz'08]

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[Bell,Lee,Makris et al.'23]

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$$
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$$

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[Intro](#page-2-0) [Details](#page-6-0) [RRV](#page-12-0) [RRR](#page-19-0) [Results](#page-39-0)

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Generalization to N3LO 1-jettiness

- Most complicated real contribution from dipole terms with emissions between i, j lines only
- For each soft momenta k and dipole eikonal factor S_{ij} dependent on p_i,p_j only with $\Theta_{ij}=\theta\left(k\cdot p_i-k\cdot p_j\right)$

$$
\left[\delta\left(\tau-k\cdot p_i-\dots\right)\Theta_{mi}\Theta_{ji}+\delta\left(\tau-k\cdot p_j-\dots\right)\Theta_{mj}\Theta_{ij}+\delta\left(\tau-k\cdot p_m-\dots\right)\Theta_{im}\Theta_{jm}\right]S_{ij}
$$

■ With $\Theta_{\text{mx}} = 1 - \Theta_{\text{xm}}$ most singular contributions coincide with zero-jettiness contributions

$$
\big[\delta\,(\tau-k\cdot p_i-\dots)\Theta_{ji}+\delta\,\big(\tau-k\cdot p_j-\dots\big)\Theta_{ij}\,\big]S_{ij} + \text{less singular}
$$

Conclusion

- Zero-jettiness slicing scheme is pushed from N2LO to N3LO level with the last missing ingredient calculated
	- $-$ Thrust resummation in $\mathrm{e}^+\mathrm{e}^-$ annihilation and Higgs decay
	- [−] Differential cross section predictions for DIS and VBF
- **Developed techniques**
	- [−] For efficient reduction of phase-space integrals with Heaviside *θ*-functions constraints in the presence of loop corrections and additional regulators
	- [−] For the high precision numerical solution of differential equations for auxiliary integrals, making possible most complicated master integrals computation
	- [−] For calculation of the large number of highly divergent integrals required for boundary conditions and master integrals without complicated dependence on soft partons momenta

Thank you for your attention!